Appendix A - Description of the subject of the contract for the delivery of precision positioning stages for the PolyX beamline at the SOLARIS National Synchrotron Radiation Centre

# A 5-axis system for sample positioning

The 5-axis system will be used for sample positioning for µXRF, µXRF-CT, µCT and newly developed sub-micron multi-beam microscopy with polycapillary optics with sub-micrometer precision. The scheme of the system is presented in Fig.1. The order of the stages and their dimensions result from required travel ranges, space restrictions and possible collisions with optics and detectors. Height of the systems should be hmin=(335+/-10) mm in the lowest Z stage position.

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| **Figure 1.** The 5-axis system for sample positioning |

## Purpose of the stages:

Stage Y: precisely moves the sample along the beam direction,

Stage Z: change the height between experimental modes and slow scanning (~1 mm/s speed),

Stage qX: alignment of the rotation axis perpendicular to the beam,

Stage X: sample centering and faster scanning (~10 mm/s)

Stage qZ: sample rotation.

## Specifications of stages in the 5-axis system:

### Y-stage:

|  |  |
| --- | --- |
| Example | LINEAR STAGE HUBER 5101.35-150X2 with absolute encoder |
| Table size [W x L]  | 170 mm x 170 mm |
| Travel range  | +/- 75 mm |
| Width | 170 mm |
| Height [without motor] | < =70 mm |
| Length [without motor] | <=350 mm |
| Accuracy – open loop | +/-8 µm |
| Repeatability (unidir.) open loop | +/- 2 µm |
| Reversal error open loop  | 4 µm |
| Material (base/slide) | Al |
| Max. load | 1500 N |
| Min. drive torque | 0.6 Nm |
| Stiffness | 0.7 ”/Nm |
| Weight [without motor] | < 10 kg |
| Motor:  | e.g. VEXTA PKP266 D14BA2 (TS 78411) 120 Ncm, flange 56 mm, 200/400 steps/rev. Double Shaft. Connectors: see Appendix CS1 |
| Encoder:  | Renishaw Resolute, BISS-C, 32-bit, 5 nmor equivalent, SUB-D9 connector,cable up to 5 m. |
| Limit switches | Adjustable, mechanical, NC |

### Z-stage

|  |  |
| --- | --- |
| Example  | Z-STAGE HUBER 5103.A20-90X2 with absolute encoder, Pitch 0.06 mmCustom tapped hole pattern for mounting of 1-Circle Segment 5202.60 |
| Travel range  | +/- 45 mm |
| Pitch  | 0.06 mm |
| Table size  | 170 mm x 170 mm |
| Width | <=170 mm |
| Height [at lowest position] | <= 140 mm |
| Length [without motor] | <=170 mm |
| Accuracy – open loop | +/-3 µm |
| Repeatability (unidir.) open loop | +/-1 µm |
| Reversal error open loop  | 8 µm |
| Material (base/slide) | Al |
| Max. load | 1500 N |
| Min. drive torque | 0.3 Nm |
| Stiffness | 2.5 ”/Nm |
| Weight [without motor] | <= 11 kg |
| Motor:  | e.g. VEXTA PKP266 D14BA2 (TS 78411)120 Ncm, flange 56 mm, 200/400 steps/rev. Double Shaft.Connectors: see Appendix CS1 |
| Encoder:  | Renishaw Resolute, BISS-C, 32-bit, 5 nmor equivalent, SUB-D9 connector,cable up to 5 m. |
| Limit switches | Adjustable, mechanical,NC |

### qX -Tilt

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| --- | --- |
| Example | CIRCLE SEGMENT HUBER 5202.60-X1Custom tapped hole pattern for mounting 5101.10-100 AND 5101.20-100  |
| Travel range  | +/-14° |
| Table size  | 100 mm x 100 mm |
| Height [without motor] | < 42 mm |
| Accuracy – open loop | +/- 25’’ |
| Gear | 360:1 |
| Height of rotation  | 110 mm |
| Repeatability (unidir.) open loop | +/-3 ‘’ |
| Reversal error open loop  | 6 ‘’ |
| Material (housing/worm gear) | Bronze |
| Max. load | 500 N |
| Min. drive torque | 0.45 Nm |
| Weight [without motor] | <= 4 kg |
| Motor:  | e.g. VEXTA PKP244D15B248 Ncm, flange 42 mm, 200/400 steps/rev. Connectors: see Appendix CS1 |
| Encoder:  | None |
| Limit switches | Adjustable, mechanical.NC |

### X-stage:

|  |  |
| --- | --- |
| Example | LINEAR STAGE 5101.10-100X2 with absolute encoder |
| Travel range  | 100 mm |
| Table size  | 80 mm x 81 mm |
| Width | <81 mm |
| Height [without motor] | < 35 mm |
| Length [without motor] | <220 mm |
| Accuracy – open loop | +/-15 µm |
| Repeatability (unidir.) open loop | +/-2 µm |
| Reversal error open loop  | 4 µm |
| Material (base/slide) | Al |
| Max. load | 250 N |
| Min. drive torque | 0.1 Nm |
| Stiffness | 4 ”/Nm |
| Weight [without motor] | < 2 kg |
| Motor:  | e.g. VEXTA PKP223D15B25 Ncm, flange 28 mm, 200/400 steps/rev. Connectors: see Appendix CS1 |
| Encoder:  | Renishaw Resolute, BISS-C, 32-bit, 5 nmor equivalent, SUB-D9 connector,cable up to 5 m. |
| Limit switches | Adjustable, mechanical |

### qZ-rotation

|  |  |
| --- | --- |
| Example | 1-CIRCLE GONIOMETER 408 X3 W2 with absolute encoder + adapter for mounting on 5101.10-100 stage |
| Travel range  | 360° |
| Table size  | <=80 mm dimater |
| Height [without motor] | < 50 mm |
| Accuracy – open loop | +/-25’’ |
| Gear | 180:1 |
| Repeatability (unidir.) open loop | +/-2 ‘’ |
| Reversal error open loop  | 10‘’ |
| Eccentricity | 2 µm |
| Wobble | 8’’ |
| Material (housing/worm gear) | Aluminium/Bronze |
| Max. load (hot/ver) | 400 N/125 N |
| Min. drive torque | 0.05 Nm |
| Weight [without motor] | <= 1.5 kg |
| Motor:  | e.g. VEXTA PKP223D15B25 Ncm, flange 28 mm, 200/400 steps/rev. Connectors: see Appendix CS1 |
| Encoder:  | Renishaw with Resa-scale BISS-C, 32-bit, or eqivalent |
| Limit switches | mechanical.NC |

# A 2-axis system for detector positioning with respect to the SAMPLE

The 2-axis system will be used for positioning of two detectors: a hybrid pixel detector and a x-ray microscope with a camera. The load on the system will be from 30-50 kg and the torque MX will be 30-50 Nm. The 2-axis system is presented in Figure 2.

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| Obraz zawierający meble, stół  Opis wygenerowany automatycznie |
| **Figure 2** The 2-axis system for detector positioning |

## Specifications of stages in the 2-axis system:

### X-Stage

|  |  |
| --- | --- |
| Example | LINEAR STAGE HUBER 5101.35-300X1 with absolute encoder |
| Table size [W x L]  | 170 mm x 170 mm |
| Travel range  | +/- 150 mm |
| Width | 170 mm |
| Height [without motor] | < 70 mm |
| Length [without motor] | <350 mm |
| Accuracy – open loop | +/-20 µm |
| Repeatability (unidir.) open loop | +/-3 µm |
| Reversal error open loop  | 6 µm |
| Material (base/slide) | Al |
| Max. load | 1500 N |
| Min. drive torque | 0.6 Nm |
| Stiffness | 0.7 ”/Nm |
| Weight [without motor] | < 15 kg |
| Motor:  | e.g. VEXTA PKP266 D14BA2 (TS 78411) 120 Ncm, flange 56 mm, 200/400 steps/rev. Double Shaft.Connectors: see Appendix CS1 |
| Encoder:  | Renishaw Resolute, BISS-C, 32-bit, 5 nmor equivalent, SUB-D9 connector,cable up to 5 m. |
| Limit switches | Adjustable, mechanical, NC |

### Z-stage

|  |  |
| --- | --- |
| Example  | Z-STAGE HUBER 5103.A20-40X1 with absolute encoder, Pitch 0.02 mm |
| Travel range  | +/- 20 mm |
| Pitch  | 0.02 mm |
| Table size  | 170 mm x 170 mm |
| Width | <=170 mm |
| Height [at lowest position] | <= 90 mm |
| Length [without motor] | <=170 mm |
| Accuracy – open loop | +/-5 µm |
| Repeatability (unidir.) open loop | +/-3 µm |
| Reversal error open loop  | 12 µm |
| Material (base/slide) | Al |
| Max. load | 1500 N |
| Min. drive torque | 0.3 Nm |
| Stiffness | 1.5 ”/Nm |
| Weight [without motor] | <= 7.5 kg |
| Motor:  | e.g. VEXTA PKP266 D14BA2 (TS 78411)120 Ncm, flange 56 mm, 200/400 steps/rev. Double Shaft.Connectors: see Appendix CS1 |
| Encoder:  | Renishaw Resolute, BISS-C, 32-bit, 5 nmor equivalent, SUB-D9 connector,cable up to 5 m. |
| Limit switches | Adjustable, mechanical,NC |

# Motors and connectors

1. Solaris standards are described in Appendix CS1 (similar to ESRF/MAXLAB). After agreement different solutions can be also considered
2. All motors should be 2-phase (bipolar) stepper motor suited for micro-stepping (eg. Vexta PK….).
3. Motor connectors should be military as described in CS1, for smaller stages SUB-D15 connectors are acceptable.

# Design

After signing the contract, the supplier should provide a 3D step model of both systems, their wiring schemes, and most important motorization parameters from table in Section 10.3 of Appendix CS1. Manufacturing is possible only after approval of the design by SOLARIS.

# Test and MounTing

All stages should be tested at factory. Motors and encoders should be mounted.